

FIGURE 1

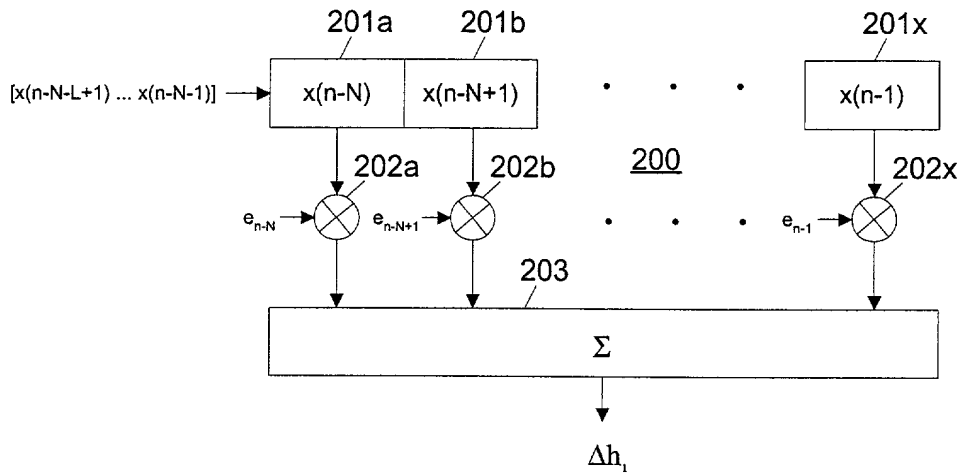


FIGURE 2A

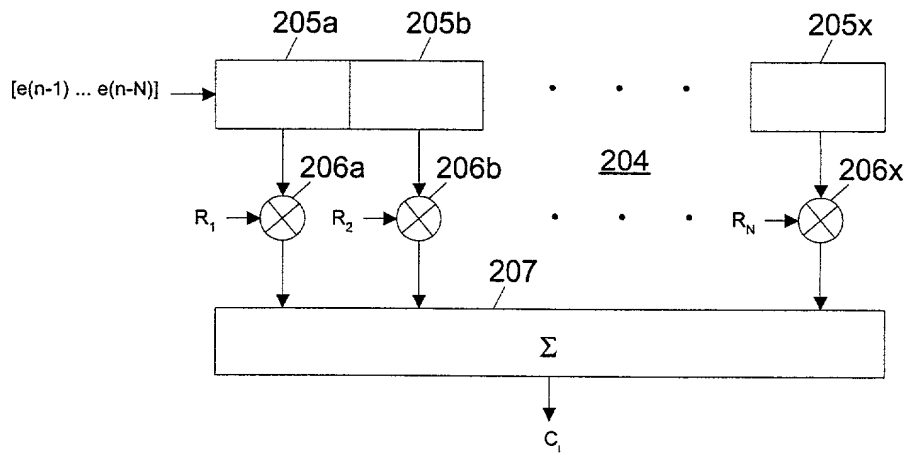


FIGURE 2B

FIGURE 3

The diagram illustrates a control system 500. It features a feedforward path 501a containing block 200 (\bar{h}_f). A disturbance path 501b includes block 213 ($f(\cdot)$) and block 211 (\bar{h}_b). A feedback path 501c contains block 215a (\bar{e}). A disturbance feedback path 501d contains block 215b (\bar{e}). The system also includes a summing junction 210 and a plant block 214 ($g(\cdot)$). The input x is split to the feedforward path and the main summing junction. The output y is fed back to the disturbance path and the feedback path. The error signal e_i is the output of the main summing junction.

FIGURE 5

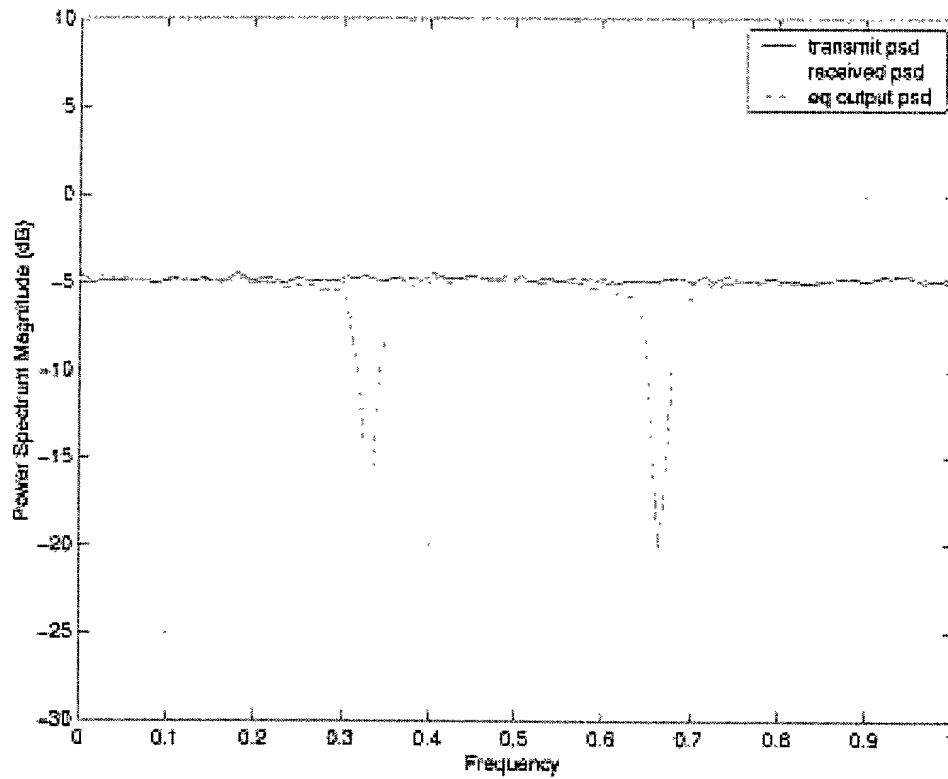


FIGURE 6

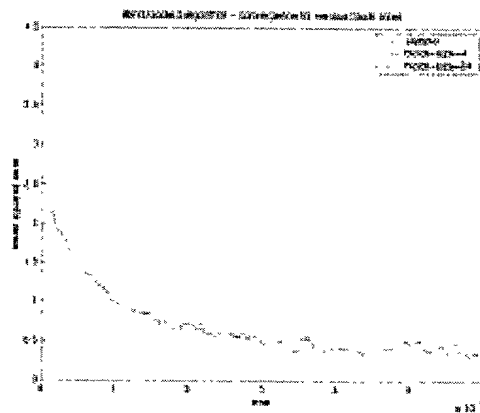


FIGURE 7

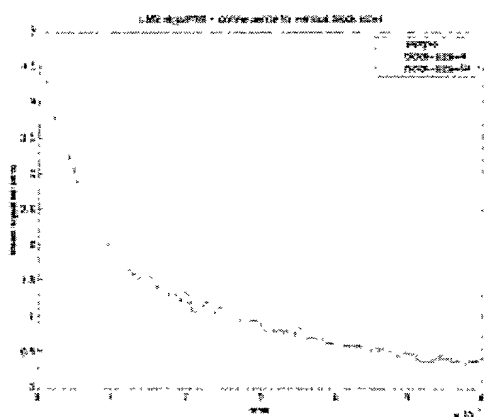


FIGURE 8

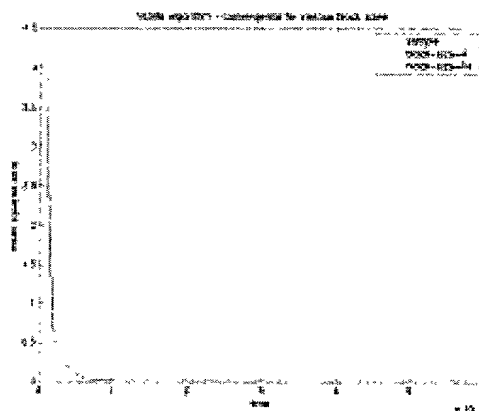


FIGURE 9

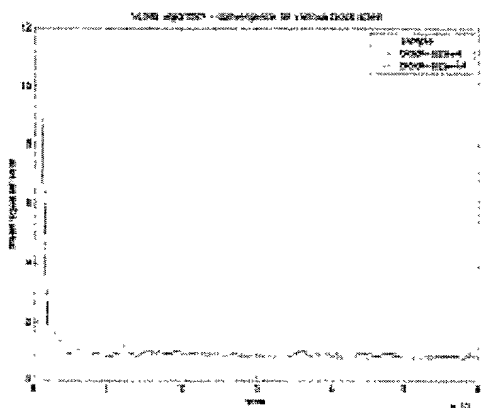


FIGURE 10